

MetaDriverse: Open Source Simulation Platform for AI Research on Autonomous Driving PI: Bolei Zhou (UCLA), Co-PI: Trevor Darrell and Angjoo Kanazawa (UC Berkeley)

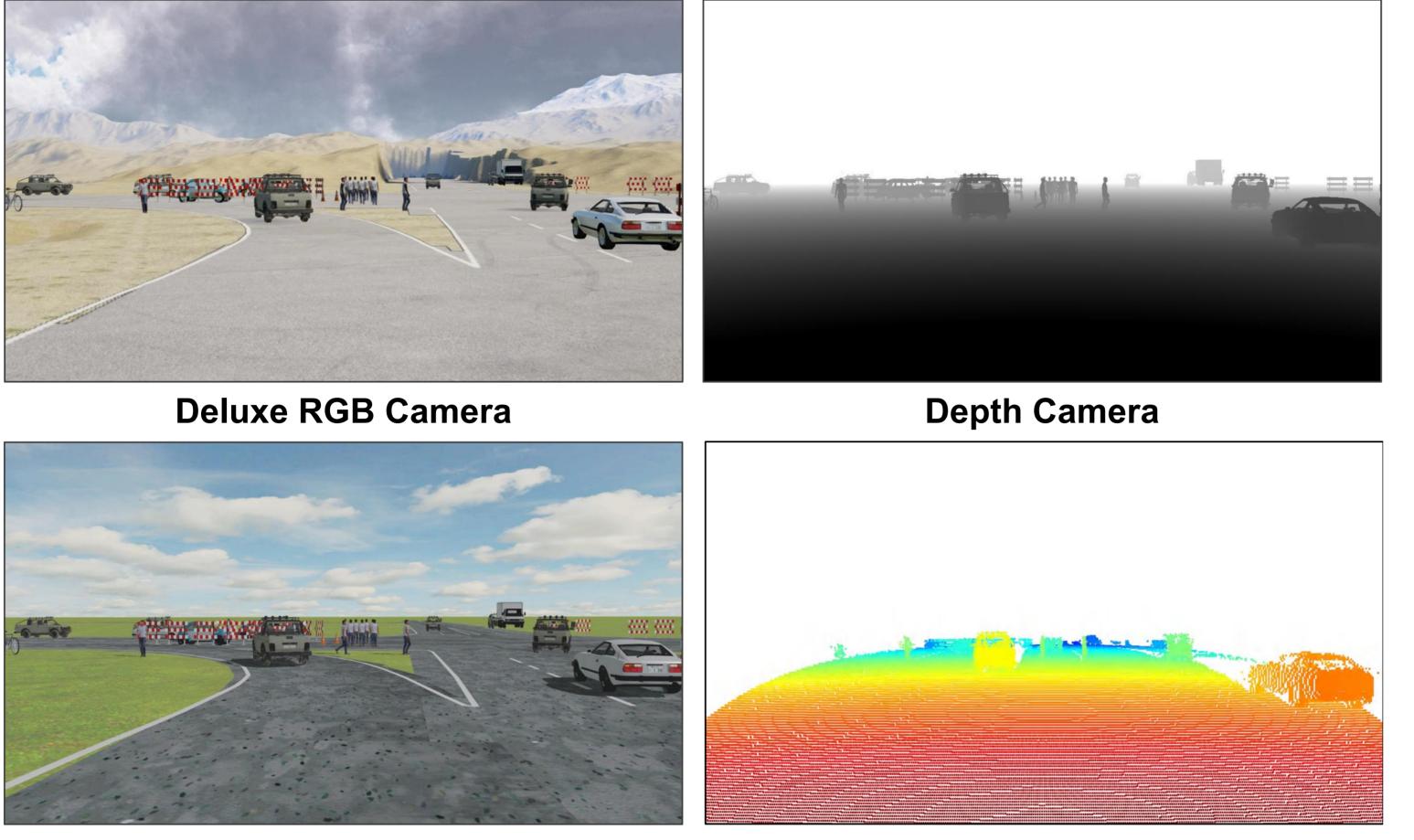
Infrastructure Overview

• A lightweight and flexible driving simulator for research



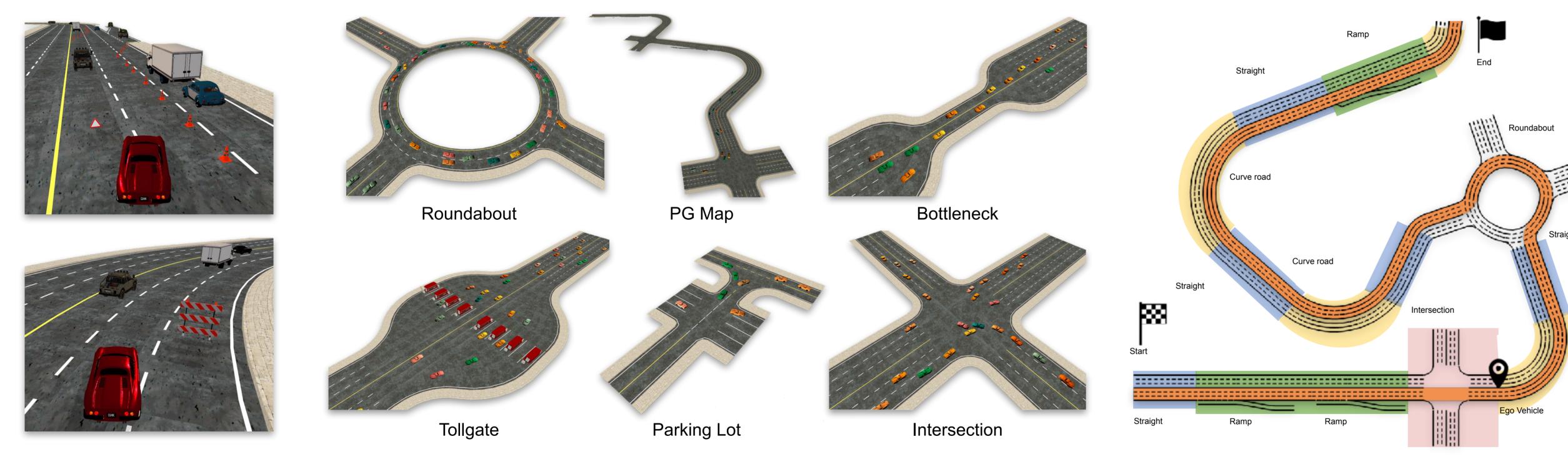


Top-down Rendering



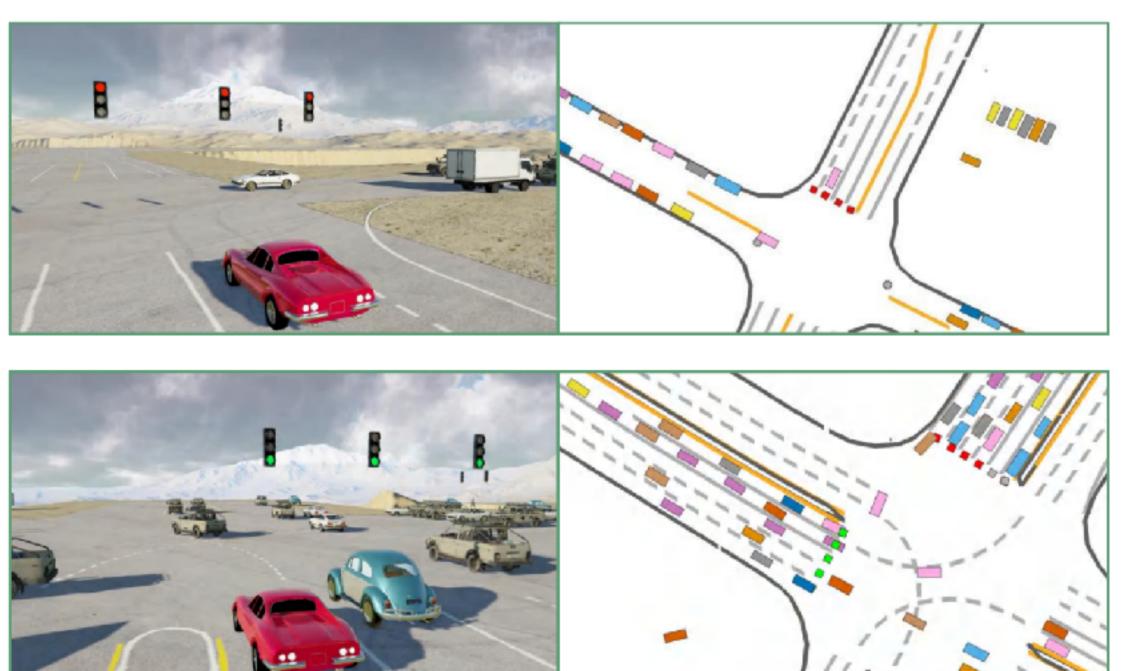
Light RGB Camera

Statistics: Downloads: 14,389, Github stars: 447, Citations: 92 Multiple simulation environments



Interactive objects

Multi-agent simulation

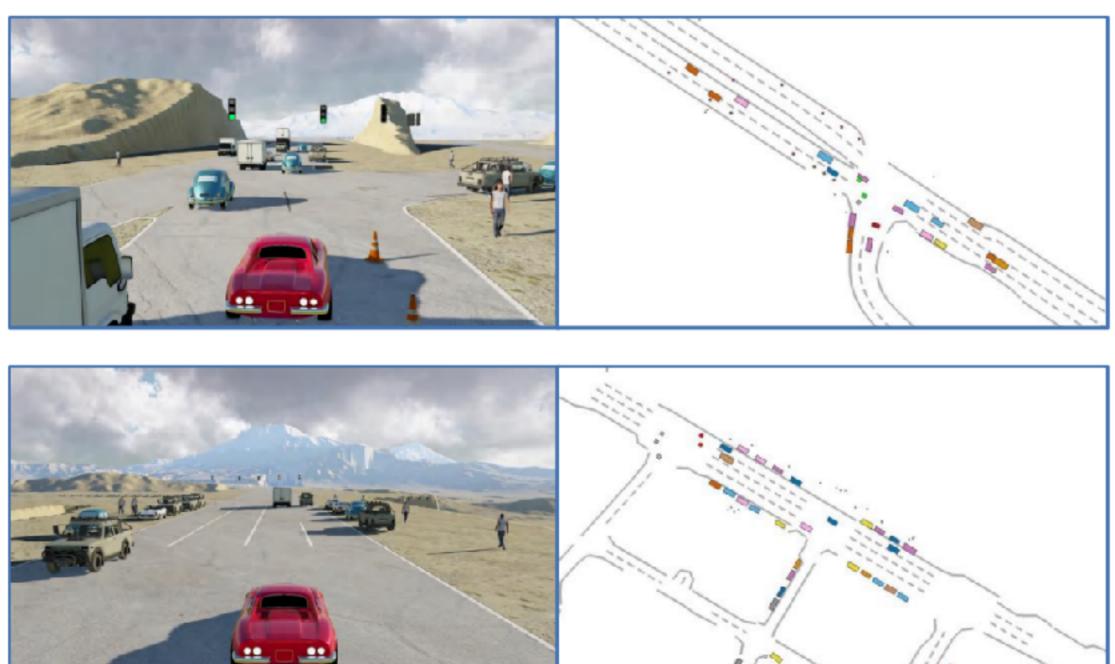


Traffic scenarios from Waymo Open dataset

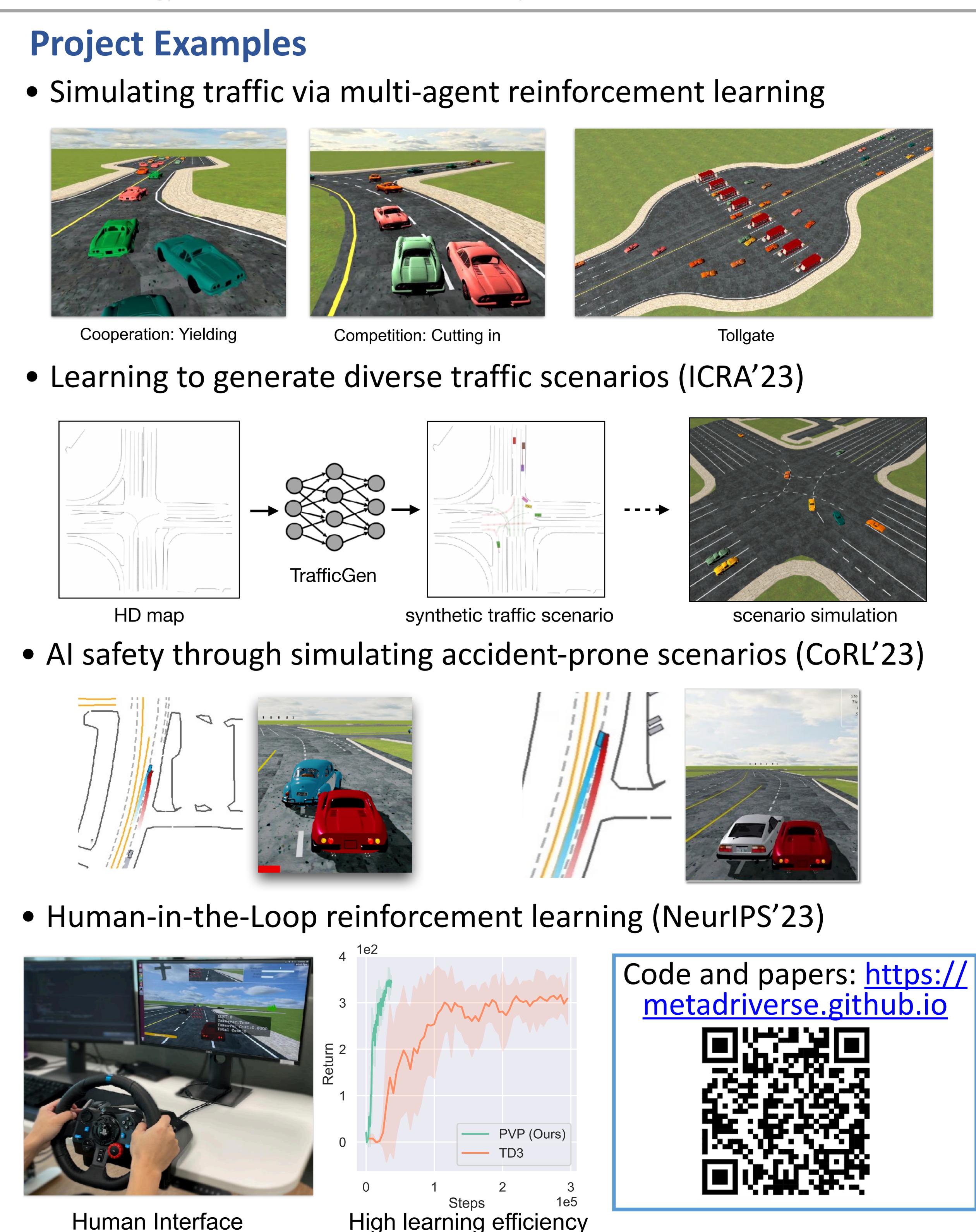
3D Lidar

Procedure generation

• ScenarioNet: diverse traffic scenario data from real-world (NeurIPS'23) 500-hour replays from Waymo Open dataset, 1500-hour replays from Nuplan dataset, and more



Traffic scenarios from NuPlan dataset



Human Interface Project is supported by the NSF under Grant No. 2235012 and 2235013

